

#### Chapter 4 Bandpass signaling principles and circuits



In this section, we will answer the questions:

What is a general representation for bandpass digital and analog signals?

How do we represente a modulated signal?

How do we represent bandpass noise?







#### **Modulation**

The process of imparting the source information onto a bandpass signal with a carrier frequency f<sub>c</sub> by the introduction of amplitude or phase perturbations or both.

The modulation may be visualized as a mapping operation that maps the source information onto the bandpass signal.



#### The modulated signals representation

$$v(t) = R(t) \cos[\omega_c t + \theta(t)]$$

$$v(t) = x(t)\cos\omega_c t - y(t)\sin\omega_c t$$

 $x(t) = R(t)\cos\theta(t)$  $y(t) = R(t)\sin\theta(t)$ 

 $v(t) = \operatorname{Re}\left\{g(t)e^{j\omega_{c}t}\right\}$ 

$$g(t) = R(t)e^{j\theta(t)}$$
$$= R(t)\left[\cos\theta(t) + j\sin\theta(t)\right]$$
$$= x(t) + jy(t)$$
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#### Theorem

## Any physical bandpass waveform can be represented by

$$v(t) = \operatorname{Re}\left\{g(t)e^{j\omega_{c}t}\right\}$$

#### Two other equivalent representations:

$$v(t) = R(t) \cos[\omega_c t + \theta(t)]$$

$$v(t) = x(t)\cos\omega_c t - y(t)\sin\omega_c t$$





## 4.2 Representation of modulated signals





The modulated signal is represented by

$$s(t) = \operatorname{Re}\left\{g(t)e^{j\omega_{c}t}\right\}$$

where the complex envelope g(t) is a function of the modulating signal m(t):

$$g(t) = g\big[m(t)\big]$$

g[.] performs a mapping operation on m(t)



## 4.2 Representation of modulated signals

**Properties of complex envelope g(t):** 

$$g(t) = x(t) + jy(t) = R(t)e^{j\theta(t)}$$

$$x(t) = \operatorname{Re}\left\{g(t)\right\} = R(t)\cos\theta(t)$$
$$y(t) = \operatorname{Im}\left\{g(t)\right\} = R(t)\sin\theta(t)$$

$$y(t) = \operatorname{Im}\{g(t)\} = R(t)\sin\theta(t)$$

$$R(t) = |g(t)| = \sqrt{x^2(t) + y^2(t)}$$

$$\theta(t) = \tan^{-1} \left( \frac{y(t)}{x(t)} \right)$$





# 4.3 Spectrum of bandpass signals



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#### 4.3 Spectrum of bandpass signals

a bandpass wavefor  $v(t) = \operatorname{Re}\left\{g(t)e^{j\omega_c t}\right\}$ 

if 
$$v(t) \leftrightarrow V(f)$$
  
 $g(t) \leftrightarrow G(f)$   $\longrightarrow$  then  $V(f)$   $\underbrace{\widetilde{2}}_{p_v(f)} G(f)$ 

#### the spectrum of the bandpass waveform is

$$V(f) = \frac{1}{2} \Big[ G(f - f_c) + G^*(-f - f_c) \Big]$$

#### the PSD of the waveform is

$$p_{v}(f) = \frac{1}{4} \left[ p_{g}(f - f_{c}) + p_{g}(-f - f_{c}) \right]$$



4.3 Spectrum of bandpass signals

#### the PSD of the waveform is

$$p_{v}(f) = \frac{1}{4} \Big[ p_{g}(f - f_{c}) + p_{g}(-f - f_{c}) \Big]$$

The total average normalized power of a bandpass waveform v(t) is

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$$P_{v} = \left\langle v^{2}(t) \right\rangle$$
$$= \int_{-\infty}^{+\infty} p_{v}(f) df$$
$$= R_{v}(0)$$
$$= \frac{1}{2} \left\langle \left| g(t) \right|^{2} \right\rangle$$





# The peak envelope power (PEP) is the average power that would be obtained if |g(t)| were to be held constant at its peak value

The normalized PEP is given by

$$P_{PEP} = \frac{1}{2} \left[ \max \left| g(t) \right| \right]^2$$



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#### **Evaluation of power**

Example
 Evaluate the
 magnitude
 spectrum for an
 amplitude modulated (AM)
 signal.



(b) Magnitude Spectrum of AM Signal

Figure 4–2 Spectrum of AM signal.



#### 4.5 Bandpass filtering and linear distortion



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#### Bandpass filtering and linear distortion

#### **Equivalent Low-pass filter**

 $v_1(t) = \operatorname{Re}\left[g_1(t)e^{j\omega_c t}\right]$ 

Bandpass filter  

$$h_1(t) = \operatorname{Re} \left[ k_1(t) e^{j\omega_c t} \right]$$

$$H(f) = 1/2K(f - f_c) + 1/2K^*(-f - f_c)$$

$$v_2(t) = \operatorname{Re}\left[g_2(t)e^{j\omega_c t}\right]$$

(a) Bandpass Filter



(b) Typical Bandpass Filter Frequency Response

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#### Bandpass filtering and linear distortion

#### Theorem

The complex envelopes for the input, output, and impulse response of a bandpass filter are related by

$$\frac{1}{2}g_2(t) = \frac{1}{2}g_1(t) * \frac{1}{2}k(t)$$

where  $g_1(t)$  is the complex envelope of the input and k(t) is the complex envelope of the impulse response. It also follows that

$$\frac{1}{2}G_2(f) = \frac{1}{2}G_1(f)\frac{1}{2}K(f)$$



#### Bandpass filtering and linear distortion

#### **Equivalent Low-pass filter**



(c) Equivalent (Complex Impulse Response) Low-pass Filter



(d) Typical Equivalent Low-pass Filter Frequency Response

#### **Linear distortion**

To have no distortion at the output of a linear time-invariant system, two requirements must be satisfied:

The amplitude response is flat. That is,

$$|H(f)| = A$$
 A: constant

The phase response is a linear function of frequency. That is,

$$\theta(f) = \angle H(f) = -2\pi f T_d$$



#### **Linear distortion**

**\*** For distortionless transmission of bandpass signals, the channel transfer function  $H(f) = |H(f)|e^{j\theta(f)}$  needs to satisfy the following requirements:

The amplitude response is constant.

$$|H(f)| = A \tag{4-27a}$$

• The derivative of the phase response is a constant.  $1 d\theta(f)$ 

$$-\frac{1}{2\pi}\frac{d\theta(f)}{df} = T_g$$

(4-27b)



#### Linear distortion

#### Note:

The Eqs. (4-27a) and (4-27b) are only sufficient requirements for distortionless transmission of bandpass signals.



#### **Linear distortion**

The output bandpass signal can be described by

$$v_2(t) = Ax(t - T_g) \cos\left[\omega_c(T - T_d)\right] - Ay(t - T_g) \sin\left[\omega_c(t - T_d)\right]$$

The bandpass filter delays the input complex envelope (i.e., the input information) by T<sub>g</sub>, whereas the carrier is delayed by T<sub>d</sub>.

\* Note:  $T_g$  will differ from  $T_d$ , unless  $\theta_0$  happens to be zero.



#### Linear distortion



- The general requirements for distortionless transmission of either baseband or bandpass signals are given by Eqs. (2-150a) and (2-150b).
- However, for the bandpass case, Eq.(2-150b) is overly restrictive and may be replaced by Eq.(4-27b).
- For distortionless bandpass transmission, it is only necessary to have a transfer function with a constant amplitude and a constant phase derivative over the bandwidth of the signal.



#### 4.6 Bandpass sampling theorem



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### 4.6 Bandpass sampling theorem

#### **Bandpass sampling Theorem**

• If a (real) bandpass waveform has a nonzero spectrum only over the frequency interval  $f_1 < |f| < f_2$ , where the transmission bandwidth  $B_T$  is taken to be the absolute bandwidth  $B_T = f_2 - f_1$ , then the waveform may be reproduced form sample values if the sampling rate is

$$f_s \geq 2B_T$$



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#### 4.6 Bandpass sampling theorem

• Proof.

the quadrature bandpass representation is

$$v(t) = x(t)\cos\omega_c t - y(t)\sin\omega_c t$$

sampling theorem

$$v(t) = \sum_{n=-\infty}^{\infty} \left[ x(\frac{n}{f_b}) \cos \omega_c t - y(\frac{n}{f_b}) \sin \omega_c t \right] \left[ \frac{\sin\{\pi f_b(t - (n/f_b))\}}{\pi f_b(t - (n/f_b))} \right]$$

• For the general case, where the  $x (n/f_b)$  and  $y (n/f_b)$ samples are independent, two real samples are obtained for each value of n, so that the overall sampling rate for v(t) is  $f_s = 2f_b \ge 2B_T$ 



#### Example SA 4.5

The signal s(t) is to be sampled by using any one of three methods, for each of three sampling methods, determine the minimum sampling frequency required.



|S(f)|

BT

 $f_c$  f —

Sampler

Quad-phase sampled output

(c) Method III-IQ (in-phase and quad-phase) sampling

Figure 4–32 Three methods for sampling bandpass signals.

Low-pass filter

#### Bandpass dimensionality theorem

#### \* Bandpass dimensionality theorem

Assume that a bandpass waveform has a nonzero spectrum only over the frequency interval  $f_1 < |f| < f_2$ , where the transmission bandwidth  $B_T$  is taken to be the absolute bandwidth given by  $B_T = f_2$  $f_1$  and  $B_T < < f_1$ , the waveform may be completely specified over a  $T_0$ -second interval by

$$N = 2B_T T_0$$

independent pieces of information. *N* is said to be the number of dimensions



#### 4.7 Received signal plus noise



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The signal out of the transmitter is

$$s(t) = \operatorname{Re}\left\{g(t)e^{j\omega_{c}t}\right\}$$

The received signal plus noise is

$$r(t) = s(t) * h(t) + n(t)$$

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If the channel is distortionless,  $H(f) = Ae^{j(-2\pi fT_g + \theta_0)} = (Ae^{j\theta_0})e^{-j2\pi fT_g}$ the signal plus noise at the receiver input is

$$r(t) = \operatorname{Re}\left\{Ag(t - Tg)e^{j(\omega_{c}t + \theta(f))}\right\} + n(t)$$

# 4.7 Received signal plus noise

✤ If the receiver circuits are designed to make errors due to the channel group delay ( $T_g$ ) and  $\theta(f)$  effects negligible, we can consider the signal plus noise at the receiver input to be

$$r(t) = \operatorname{Re}\left\{g(t)e^{j\omega_{c}t}\right\} + n(t)$$

where the effects of channel filtering, if any, are included by some modification of the complex envelope g(t).



